

# Lorentzian asymptotic safety on curved backgrounds

Kasia Rejzner

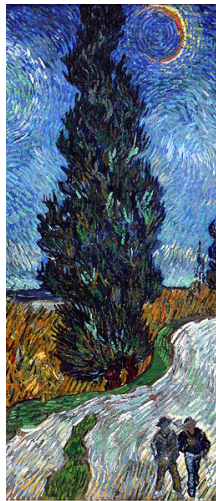
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## 1 Introduction

## 2 Flow equations

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- The theory is power-counting non-renormalisable, so either we treat it as an **effective theory** [Bjerrum-Bohr, Donoghue, ...], or we look for a non-Gaussian fixed point (**asymptotic safety**) [Wetterich, Reuter, Saueressig, Eichhorn, Reichert, Held, Knorr, Platania. . .]



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- Some things to consider: Lorentzian signature, background independence, gauge invariant observables, locality vs non-locality.



# Algebraic QFT on curved spacetimes

- Before we get to QG: **QFT on curved spacetimes**. Many of its conceptual problems can be solved in the **algebraic approach**. [Hollands, Wald, Brunetti, Fredenhagen, Verch, Fewster, Dappiaggi, Pinamonti, ...].

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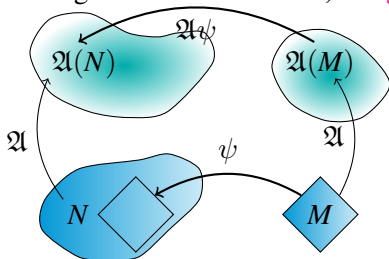


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- The main idea is to encode physical information in **algebras**  $\mathfrak{A}(\mathcal{O})$  (interpreted as algebras of observables) **assigned to open regions**  $\mathcal{O} \subset M$ .

## Main advantage

Construction of **observables**  $\mathfrak{A}(\mathcal{O})$  is independent from the construction of **states**. Entanglement and superposition are properties of states (always non-local) not of observables (often local).

# Perturbative algebraic quantum field theory



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  - Interaction introduced in the causal approach to **renormalization due to Epstein and Glaser** ([Epstein-Glaser 73]),
  - Generalization to gauge theories using homological algebra ([Hollands 08, Fredenhagen-KR 11]).



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- Typically  $\mathcal{E}(M)$  is a space of smooth sections of some vector bundle  $E \xrightarrow{\pi} M$  over  $M$ . For the scalar field:  $\mathcal{E}(M) \equiv C^\infty(M, \mathbb{R})$ . For perturbative gravity  $\mathcal{E}(M) = \Gamma((T^*M)^{\otimes 2})$ .

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- The choice of action functional  $I$  specifies the **dynamics**. We use a modification of the Lagrangian formalism (fully covariant).

# Building models in pAQFT I



- We model observables as functionals  $\mathcal{F}(M)$  on the space  $\mathcal{E}(M)$  of all possible (off-shell) field configurations.

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- On  $\mathcal{F}(M)$  we introduce first **classical** dynamics by means of a Poisson structure (**Peierls bracket**):  $\{F, G\} = \left\langle \frac{\delta F}{\delta \varphi}, \Delta \frac{\delta G}{\delta \varphi} \right\rangle$ ,  
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- Use the deformation quantization to construct the non-commutative algebra  $\mathfrak{A}(M) = (\mathcal{F}(M)[[\hbar]], \star)$ , such that

$$F \star G \xrightarrow{\hbar=0} FG \quad \frac{1}{i\hbar}(F \star G - G \star F) \xrightarrow{\hbar=0} \{F, G\}.$$

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- We work all the time on the **same vector space of functionals**, but we equip it with different algebraic structures (Poisson bracket,  $\star$ -product).



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- For a quadratic action  $I_0$  that induces hyperbolic equations of motion (e.g.  $-(\square + m^2)\varphi = 0$ ),  $\star$  can be constructed directly, starting from  $\Delta$  and choosing a **choice of a 2-point function for a quasifree Hadamard state**:  $\Delta^+ = \frac{i}{2}\Delta + H$ .

$$F \star_H G \doteq m \circ e^{\hbar \langle \Delta^+, \frac{\delta}{\delta\varphi} \otimes \frac{\delta}{\delta\varphi} \rangle} (F \otimes G),$$

# Time-ordered products

- Take an interaction  $V \in \mathcal{F}_{\text{loc}}(M)$  and define the **formal S-matrix**

$$\mathcal{S}(\lambda V) \doteq \sum_{n=0}^{\infty} \frac{1}{n!} \left( \frac{i\lambda}{\hbar} \right)^n V \cdot_{\mathcal{T}} \dots \cdot_{\mathcal{T}} V,$$

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- We also introduce the **time-ordering map**  $\mathcal{T}$ , so that  $F \cdot_{\mathcal{T}} G = \mathcal{T}(\mathcal{T}^{-1}F \cdot \mathcal{T}^{-1}G)$ . It formally corresponds to path integrating with a Gaussian measure:

$$\mathcal{T}F(0) \sim \int F(\varphi) d\mu(\varphi)$$

# Interacting fields and states I

- Define relative S-matrices by:  $\mathcal{S}_{\lambda V}(F) \doteq \mathcal{S}(\lambda V)^{-1} \star \mathcal{S}(\lambda V + F)$ ,  
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- In the algebraic approach, **states** are functionals  $\omega : \mathfrak{A}(M) \rightarrow \mathbb{C}$  with  $\omega(\mathbb{1}) = 1$  and  $\omega(A^*A) \geq 0$ . (Relation to Hilbert spaces via GNS theorem).

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- A natural state on  $\mathcal{F}(M)$  and hence  $\mathfrak{A}(M)$  is given by evaluation at a given field configuration. For the scalar field we can take  $\omega(F) = F(0)$ .



# Interacting fields and states II

- **Wightman  $n$ -point functions** of the free theory are

$$W_n(f_1, \dots, f_n) = (\Phi(f_1) \star \dots \star \Phi(f_n))(0),$$

where  $\Phi(f)(\varphi) = \int \varphi(x)f(x)d\mu(x)$ .

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- **Interacting correlation functions** are obtained as:

$$(\Phi_{\text{int}}(f_1) \star \dots \star \Phi_{\text{int}}(f_n))(0),$$

similarly for other observables in the theory.

1 Introduction

2 Flow equations

- *Wetterich equation on Lorentzian manifolds*, Edoardo D'Angelo, Nicolò Drago, Nicola Pinamonti, KR [[arXiv:2202.07580](https://arxiv.org/abs/2202.07580)]

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- We propose new flow equations that can be realized on arbitrary globally hyperbolic manifolds in any Hadamard state (examples: deSitter, thermal states).

# Generating functions

- For an arbitrary but fixed Hadamard state  $\omega$ , define:

$$Z(j) := \omega(\mathcal{S}_V(J)) = \omega[\mathcal{S}(V)^{-1} \star \mathcal{S}(V + J)] = \omega[R_V \mathcal{S}(J)],$$

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- It is a generating function for time-ordered interacting correlators:

$$\begin{aligned} \frac{\delta^n Z}{i^n \delta j(x_1) \dots \delta j(x_n)} \Big|_{j=0} &= \omega \circ R_V (\chi(x_1) \cdot_T \dots \cdot_T \chi(x_n)) \\ &= \omega_V (\chi(x_1) \cdot_T \dots \cdot_T \chi(x_n)) = \omega \circ R_V (\chi(x_1) \cdot_T \dots \cdot_T \chi(x_n)), \end{aligned}$$

where  $\omega_V \doteq \omega \circ R_V$  is the interacting state.



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- The effective action  $\tilde{\Gamma}$  is  $\tilde{\Gamma}(\phi) = W(j_\phi) - J_\phi(\phi)$ , where  $j_\phi \in C_c^\infty(M)$  is the current defined by

$$\left. \frac{\delta W}{\delta j} \right|_{j=j_\phi} = \phi,$$

for  $\phi \in \mathcal{E}$ .

# Choice of the regulator

- We use a local regulator

$$Q_k = -\frac{1}{2} \int dx q_k(x) \chi(x)^2,$$

and chose  $q_k(x) = k^2 f(x)$ , where  $f$  is a compactly supported smooth function (to be taken to 1). Compare: *Spectral functions of gauge theories with Banks-Zaks fixed points*, Yannick Kluth, Daniel F. Litim, Manuel Reichert, *Phys.Rev.D* 2023.

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- Modify the free theory:  $I_{0k} = I_0 + Q_k$ . The regularised generating functional  $Z_k$  is

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- We also have  $W_k(j) = -i \log Z_k(j)$ ,  $\tilde{\Gamma}_k(\phi) = W_k(j, \phi) - J_\phi(\phi)$  and finally we can translate  $\tilde{\Gamma}_k$  to get the *average effective action*,

$$\Gamma_k(\phi) = \tilde{\Gamma}_k(\phi) - Q_k(\phi).$$

# Flow equations I

- By definition:

$$\partial_k W_k(j) = -\frac{1}{2} \int dx \partial_k q_k(x) \frac{1}{Z_k(j)} \omega(S(V)^{-1} \star [S(V+J+Q_k) \cdot \mathcal{T} \mathcal{T} \chi^2(x)]) .$$

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- After a short computation:

$$\begin{aligned} & \partial_k \Gamma_k(\phi) \\ &= -\frac{1}{2} \int dx \partial_k q_k(x) \left[ \frac{1}{Z_k(j_\phi)} \omega(R_V(S(J_\phi + Q_k) \cdot \mathcal{T} \mathcal{T} \chi^2(x))) - \phi^2(x) \right] \\ &= \lim_{y \rightarrow x} \frac{i}{2} \int dx \partial_k q_k(x) \left[ \frac{\delta^2 W_k(j)}{\delta j(x) \delta j(y)} - i \tilde{H}_F(x, y) \right] , \end{aligned}$$

where we use an appropriate distribution  $\tilde{H}_F$ . This corresponds to a choice of normal ordering. Hence...

# Flow equations II

## Wetterich-form equation

$$\partial_k \Gamma_k = -\frac{i}{2} \int dx \partial_k q_k(x) : \left[ \Gamma_k^{(2)} - q_k \right]^{-1} :_{\tilde{H}_F}(x) ,$$





Thank you very much for your attention!